RD4740 PAVO Quick Start

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Release history

Date	Revision	Change
Sep 2007	1.0	First release
Sep 2009	1.1	Add USB boot section and delete JDI boot section

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1 Overview

JZ4740 is an embedded processor introduced by Ingenic Semiconductor Co., Ltd, which integrates a high performance and low power 32-bit MIPS core. Its main frequency is 360MHz. JZ4740 supports MMU, with 16K instruction cache and 16K data cache, and also integrates many peripherals. JZ4740 supports many Embedded Operating Systems such as Linux[™], WinCE[™], etc. This document will introduce how to use the reference design board PAVO and help readers gain a quick start of Linux and WinCE.



2 Quick start Linux

2.1 Compile U-Boot

Compile as the following step and generate the u-boot-nand.bin:

```
Firstly, prepare the U-Boot source:

# tar -xjf u-boot-1.1.6.tar.bz2

# cd u-boot-1.1.6

# gzip -cd ../u-boot-1.1.6-jz-yyyymmdd.patch.gz | patch -p1

And then Compile as following steps:

$ make pavo_nand_config

$ make
```

2.1.1 Use USB tool program u-boot

Before programming u-boot, now introduce the way of PAVO board boot from usb device:

- 1) Press **SW5** and **reset** key, if success you can see a new usb device on PC.
- 2) The SDRAM is 64MB on PAVO board. The NandFlash type is K9G8G08U0M. Rename USBBoot_PAVO.cfg to USBBoot.cfg in the toolkit. USBBoot_PAVO.cfg includes default configuration of the PAVO board.
- 3) Run usb_boot.exe, if the connection is correct, execute list command you can see the number of device is not zero.
- 4) Execute **boot** command, the following information can be seen:

USBBoot :> boot 0

Checking state of No.0 device: Unboot

Now booting No.0 device:

Download stage one program and execute at 0x80002000: Pass

Download stage two program and execute at 0x80c00000: Pass

Boot success!

Now configure No.0 device:

Now checking whether all configure args valid:

Current device information: CPU is Jz4740

Crystal work at 12MHz, the CCLK up to 336MHz and PMH_CLK up to 112MHz

Total SDRAM size is 16 MB, work in 4 bank and 16 bit mode

Nand page size 2048, ECC offset 28, bad block ID 127, use 1 plane mode

Configure success!

Execute programming command:

```
USBBoot :> nerase 0 8 0 0
```

USBBoot :> nprog 0 u-boot-nand.bin 0 0 -n



To here, the U-Boot has been programmed to target board.

The serial port's configuration is: 57600bps, 8N1

Now, connect the serial port of target board to PC, start HyperTerminal and set parameters. And then hardware reset the target board, start the U-Boot, there will be start message of U-Boot on HyperTerminal console.

2.2 Compile and start Linux

Firstly, compile and generate **uImage** as following step:

\$ tar xjf linux-2.6.24.3.tar.bz2

\$ cd linux-2.6.24.3

\$ gzip -cd ../linux-2.6.24.3-jz-yyyymmdd.patch.gz | patch -p1

\$ make pavo_defconfig

\$ make ulmage

2.2.1 Use USB tool program ulmage

Use usb boot tool program ulmage is similar to program u-boot. Because reading ulmage from NAND to SDRAM is through u-boot, so please be sure that the corresponding of the NAND configuration file between u-boot and USB boot tool.

Execute programming command:

USBBoot :> nprog 2048 ulmage 0 0 -n

To here, the ulmage has been programmed to target board too.

Execute as following to program YAFFS2 file:

USBboot :> nprog 4096 root.yaffs2 0 0 -o

After power on the board, there will be output on the console via serial port and LCD panel. After a moment, the demo of a QTOPIA application will be launched.



3 Quick start WINCE

3.1 Use USB download Bootloader

1. When you get BSP, in the PLATFORM\VENUS\Bin\USBBOOT\JZ4740directory,there is a compiled boot.nb0,execute USB_Boot.exe, you will see a command window, the following information can be seen:

Welcome!

USB Boot Host Software!

USB Boot Software current version: 1.4b

Handling user command.

USBBoot:>

2. Insert USB. if the device is not recognized, you need to install the driver that is placed in this director. Press **SW5** key, then press **reset** key, then loosen **reset** key, you will see the device icon on the PC. Enter "Boot 0" in the command line, then press enter key, the following information can be seen:

USBBoot :> boot 0

Checking state of No.0 device: Unboot

Now booting No.0 device:

Download stage one program and execute at 0x80002000: Pass

Download stage two program and execute at 0x80c00000: Pass

Boot success!

Now configure No.0 device:

Now checking whether all configure args valid:

Current device information: CPU is Jz4740

CPU IS 324740

Crystal work at 24MHz, the CCLK up to 336MHz and PMH_CLK up to 112MHz

Total SDRAM size is 16 MB, work in 4 bank and 16 bit mode

Nand page size 2048, ECC offset 3, bad block ID 127, use 1 plane mode

Configure success!

USBBoot:>

3. Enter "nprog 0 boot.nb0 0 0 -n" in the command line, the following information can be seen:

USBBoot :> nprog 0 boot.nb0 0 0 -n

Programing No.0 device...

Erasing No.0 device No.0 flash..... Finish!

Operation end position: 1

Force erase ,no bad block infomation!

Total size to send in byte is:262144

Image type: without oob

It will cause 2 times buffer transfer.

No.1 Programming... Finish! Checking...

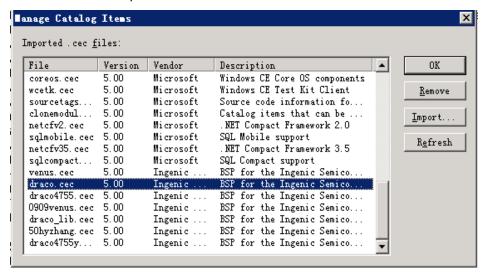
Now, we have already downloaded the boot.nb0 in the JZ4740 board successfully.



3.2 Start WinCE

1. first we can use $x \times x$.msi.msi or VENUS.cec file to install BSP, if we use VENUS.cec file ,the step is followed:

Select Manage Catalog Items from the File toolbar in the PB environment, you will see a dialog box, then import relevant cec file .the picture is showed



2. Open VENUS.bat file, define project name:

SET BSP_BASED_CHIP=JZ4740

SET BSP_BASED_BOARD=PAVO

Open JZ4740_PAVO.bat file in the \ VENUS\Files\SCRIPT directory, you can add some driver selectively, for example:

SET BSP_PAVO_WAVEDEV_INTERNAL=1

SET BSP_PAVO_MEDIA_PLAYER=1

After modification, select "Open Release Directory" from PB menu "Build OS" to enter PB50 command line, execute "set bsp" command to confirm whether the environment variable is right.

3. When the setting is OK we execute Sysgen, there is a NK.bin in the

WINCE500\PBWorkspaces\Venus\RelDir\VENUS_MIPSII_Release directory. Then select "Open Release Directory" from PB menu "Build OS" to enter PB50 command line, we don't need to change this directory, execute "getnb0.bat" command directly, a Nk.nb0 is generated in this directory.

We copy the NK.nb0 from the directory to the SD card, then reset the development board after insert the SD card to the slot.

Note: Here VENUS is project name.